

Digital Stepper Drive DR-SB060AC072D-CS

1. Introduction

Descriptions

This driver is a new generation digital 2-phase stepper motor driver, based on a 32-bit DSP processor, combination of the anti-resonance, low noise, micro-step and low temperature rise technology significantly improve the performance of the stepper motor, has low noise, small vibration, low temperature rise and high-speed torque. The driver use online adaptive PID technology, without manual adjustment can be automatically generated optimal parameters for different motors, and achieve the best performance.

Supply voltage range from 20VAC to 60VAC or from 24VDC to 90VDC, suitable for driving various 2-phase hybrid stepping motors which phase current below 7.2A. The microstep can be set from full step to 51200steps/rev and the output current can be set form 2.4A to 7.2A; with automatic idle-current reduction, self-test, overvoltage, under-voltage and over-current protection.

Features

- High-performance, low price
- micro-step
- Automatic idle-current reduction
- Optical isolating signals I/O
- Max response frequency up to 200Kpps
- Low temperature rise, smooth motion
- Online adaptive PID technology

Applications

Suitable for a variety of large-scale automation equipments and instruments. For example: labeling machine, cutting machine, packaging machine, plotter, engraving machine, CNC machine tools and so on. It always performs well when applied for equipment which requires for low-vibration, low-noise, high-precision and high-velocity.



Microstep Setting

Step/Rev	SW5	SW6	SW7	SW8
Default	on	on	on	on
800	off	on	on	on
1600	on	off	on	on
3200	off	off	on	on
6400	on	on	off	on
12800	off	on	off	on
25600	on	off	off	on
51200	off	off	off	on
1000	on	on	on	off
2000	off	on	on	off
4000	on	off	on	off
5000	off	off	on	off
8000	on	on	off	off
10000	off	on	off	off
20000	on	off	off	off
40000	off	off	off	off



3. Connectors and Pin Assignment

Control Signal connector		
Name	Description	
DIR-	Direction signal negative	
DIR+	Direction signal positive	
PUL-	Pulse signal negative	
PUL+	Pulse signal positive	
ENA-	Enable signal negative, usually left unconnected(enable)	
ENA+	Enable signal positive, usually left unconnected(enable)	

Control signal Connector

Power and Motor Connector

AC	Power supply	
AC	+24~+90 VDC or 20V-60VAC	
A+	Motor phase A	
A-		
B+	Motor phase B	
B-		



Control Signal Connector Interface

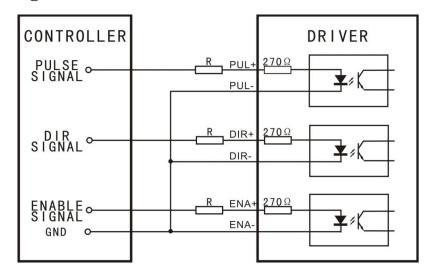


Figure 1: Common-Cathode

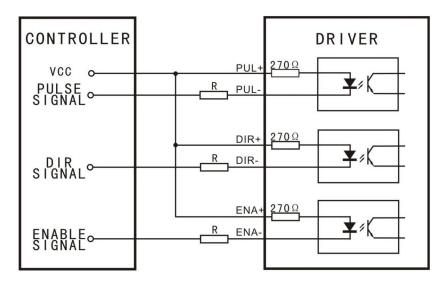


Figure 2: Common-Anode



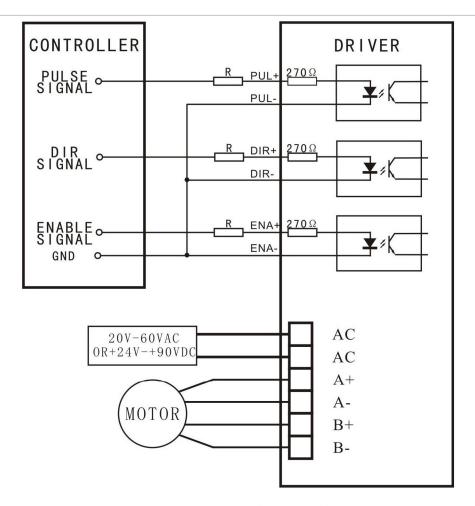


Figure 3: Typical connection

VCC	R
5V	0
12V	680Ω
24V	1.8ΚΩ

Table1



4. Problems and Solutions

problems	Possible cause	solutions	
	No power supply	Check the power supply	
Motor is not	No control signal	Check the control signal	
rotating	The driver is disabled	Don't connected the enable	
	The driver is disabled	signal or enable the driver	
	Supply voltage is too high or	Check the supply voltage	
	too low		
ALM lights	Motor line short-circuit	Check motor lines eliminate the	
	Wotor fine short-circuit	short-circuit	
	Motor line wrong connect	Check the motor wiring	
	Motor or drive failure	Replace the motor or drive	
Motor rotates in	Motor phases connected in	Reverse the phases line	
the wrong	reverse		
direction	Motor line break	Change the phases are connected	
	The Micro steps set	Set the correct segments	
Inaccurate	incorrectly.		
Position	The motor load is too heavy.	Increasing the current	
	Control signal is interfered	Eliminate interference	
	Power supply voltage too	Increasing the supply voltage	
Motor Stalled	low		
	Accelerating time is too	Extend the acceleration time-	
	short.	Extend the acceleration time	
	Current setting is too small	Increasing the current	
	Motor torque is too small	Replace the motor	



5. Mechanical Specifications (unit: mm(inch),1 inch = 25.4mm)

